



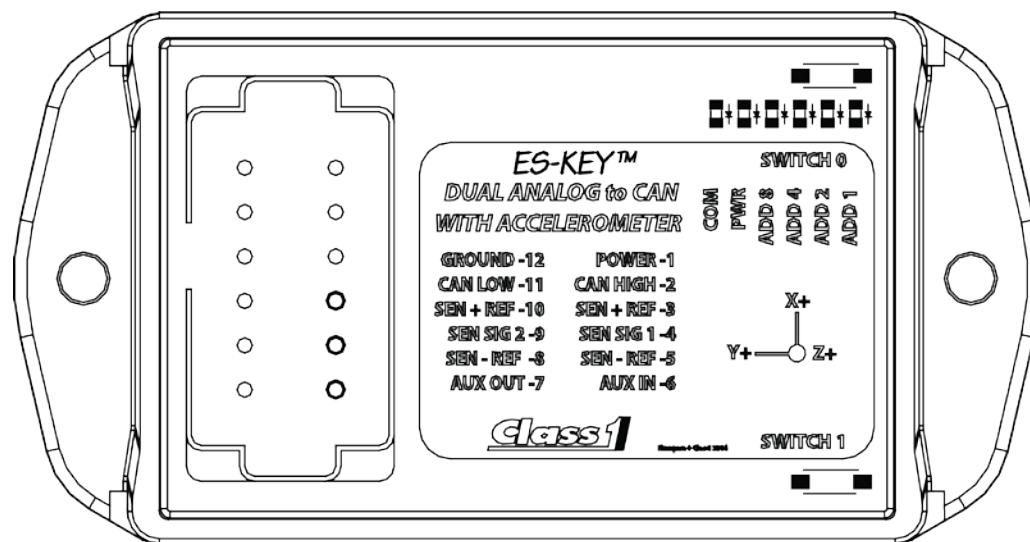
Class 1

ISO 9001 CERTIFIED

607 NW 27th Ave
Ocala, FL 34475
Phone: (352) 629-5020 or 800-533-3569
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OPERATION MANUAL

Dual Analog to CAN With Accelerometer



 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	1 of 31
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

1. REVISION LOG	3
2. SYSTEM OVERVIEW	4
2.1. SCOPE	4
2.2. PART NUMBERS.....	4
3. OPERATION	4
3.1. MODULE OPERATION.....	4
3.2. LED INDICATIONS.....	4
3.3. MAGNETIC SWITCHES	4
3.4. SHOW DEVICE ADDRESS	5
4. ANALOG CHANNEL SETUP	5
4.1. CHANNEL CONFIGURATION	5
4.1.1. <i>Analog Input Channel 0</i>	5
4.1.2. <i>Analog Input Channel 1</i>	5
4.1.3. <i>Reference Voltage Channel 0</i>	6
4.1.4. <i>Reference Voltage Channel 1</i>	6
5. MODULE CONFIGURATION	6
5.1. MODULE CONFIGURATION	6
5.1.1. <i>Normal Operation</i>	6
5.1.2. <i>Legacy 113651 Operation</i>	6
5.1.3. <i>Legacy 113652 Operation</i>	6
5.1.4. <i>Legacy 115819 Operation</i>	6
5.1.5. <i>Legacy 122397 Operation</i>	6
5.1.6. <i>Legacy mixed Operation</i>	7
6. PASSWORDS.....	7
6.1. PASSWORD LIST	7
6.2. PASSWORD ENTRY.....	8
6.3. SET MODULE OPERATION TO NORMAL.....	8
6.4. SET MODULE OPERATION TO LEGACY 113651.....	8
6.5. SET MODULE OPERATION TO LEGACY 113652.....	8
6.6. SET MODULE OPERATION TO LEGACY 115819.....	8
6.7. SET MODULE OPERATION TO LEGACY 122397.....	8
6.8. SET MODULE OPERATION TO LEGACY MIXED.....	9
6.9. SET LEGACY MODULE OPERATION TO USE BOTH CHANNELS	9
6.10. ENABLE OR DISABLE THE ACCELEROMETER IMPACT FEATURE	9
6.11. CALIBRATE X-AXIS OFFSET.....	9
6.12. CALIBRATE Y-AXIS OFFSET.....	9
6.13. ZERO CHANNEL 0 IN LEGACY MODE.....	9
6.14. ZERO CHANNEL 1 IN LEGACY MODE.....	9
6.15. INPUT POLARITY.....	9
6.16. CHANNEL 0 REFERENCE VOLTAGE ENABLE.....	10
6.17. CHANNEL 1 REFERENCE VOLTAGE ENABLE.....	10
6.18. CHANNEL 0 REFERENCE VOLTAGE SETUP	10
6.19. CHANNEL 1 REFERENCE VOLTAGE SETUP	10
6.20. CHANNEL 0 ANALOG INPUT SETUP	11
6.21. CHANNEL 1 ANALOG INPUT SETUP	11
6.22. SET ADDRESS.....	11
6.23. SET AXIS ORIENTATION.....	11

 <p>607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902</p>	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	2 of 31		
						DATE	6/21/2017	
	PRODUCT GROUP		ES-Key	P/N	FSG-MNL-00106		REV	1.08
	PRODUCT	Dual Analog to CAN with Accelerometer				BY	GMC	

6.24. BOOT LOAD.....	11
6.25. DEFAULTS	12
7. MODULE OPERATION AND DEVICE NETWORK TX RX CAN MESSAGES	13
7.1. NORMAL MODE	13
7.1.1. Accelerometer	13
7.1.2. Analog Inputs.....	13
7.1.3. Auxiliary Input.....	13
7.1.4. Auxiliary Output	13
7.2. TX INPUT STATUS MESSAGE (ES-KEY DESIGNATION 0X4X TO 0X1E).....	14
7.3. TX SOFTWARE ANGLE MESSAGE (ES-KEY DESIGNATION 0X4X TO 0XA1)	14
7.4. TX SOFTWARE VERSION MESSAGE (ES-KEY DESIGNATION 0X4X TO 0xFF)	15
7.5. TX SOFTWARE IMPACT DATA MESSAGE (ES-KEY DESIGNATION 0X4X TO 0xAA).....	15
7.6. TX SOFTWARE ANALOG DATA MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF)	16
7.7. TX SOFTWARE TILT ANGLE DATA MESSAGE (ES-KEY DESIGNATION 0X9X TO 0XA1)	16
7.8. RX USM MESSAGE (ES-KEY DESIGNATION 0X1E TO 0X4X).....	17
8. ES-KEY NETWORK DETAIL	18
8.1. INPUT/OUTPUT MEMORY SPACE.....	18
8.1.1. Standard I/O memory space	18
9. LEGACY 113651 AND LEGACY 113652 OPERATION AND DEVICE NETWORK TX RX CAN MESSAGES	19
9.1. AUXILIARY INPUT.....	19
9.2. AUXILIARY OUTPUT	19
9.3. LEGACY 113651	19
9.4. LEGACY 113652	19
9.5. TX MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF).....	20
9.6. RX MESSAGE (ES-KEY DESIGNATION 0X9F TO 0X9X).....	20
10. LEGACY 115819 DEVICE NETWORK TX RX CAN MESSAGES	21
10.1. LEGACY 115819	21
10.2. TX MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF).....	21
11. LEGACY 122397 DEVICE NETWORK TX RX CAN MESSAGES	23
11.1. LEGACY 122397	23
11.2. TX MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF).....	23
12. LEGACY MIXED DEVICE NETWORK TX RX CAN MESSAGES.....	24
12.1. LEGACY MIXED	24
12.2. TX MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF) FOR CHANNEL 0.....	24
12.3. TX MESSAGE (ES-KEY DESIGNATION 0X9X TO 0xFF) FOR CHANNEL 1	24
12.4. RX MESSAGE (ES-KEY DESIGNATION 0X9F TO 0X9X) FOR CHANNEL 1	25
13. INSTALLATION	26
13.1. MOUNTING DIMENSIONS.....	26
13.2. MOUNTING ORIENTATION	27
14. WIRING	28
14.1. DUAL ANALOG TO CAN WITH ACCELEROMETER CONNECTOR	28
14.1.1. <i>Terminating resistor requirement (CAN communication)</i>	28
14.2. SYSTEM COMPATIBILITY	28
15. UPGRADE FROM A 123394 ACCELEROMETER TO THE NEW 610-00033 DUAL ANALOG TO CAN MODULE WITH ACCELEROMETER.....	29

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	3 of 31
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017
	PRODUCT	Dual Analog to CAN with Accelerometer		REV	1.08	
				BY	GMC	

16. DIAGNOSTICS	30
17. GLOSSARY	31
18. TECHNICAL DETAILS	31
18.1. TECHNICAL DETAILS	31
18.2. WEEE (WASTE OF ELECTRICAL AND ELECTRONIC EQUIPMENT) DIRECTIVE.....	31

1. Revision Log

Rev	Date	Approved	Changes
1.00	6-30-2014	GMC	Initial requirements
1.01	8-15-2014	GMC	Added reference to additional CAN message
1.02	1-15-2015	GMC	Added reference to Zero offset in legacy O2 Mode
1.03	1-29-2015	GMC	Fixed a typo in section 6.18 and 6.19
1.04	2-19-2015	GMC	Fixed section 5.1.6 to reference both 9 volt references
1.05	3-06-2015	GMC	Added reference to being able to disable Impact Sensor
1.06	5-13-2016	GMC	Added 0-30 volt support and Tilt angle support message
1.07	9-21-2016	GMC	Added reference to Temp profile in normal mode.
1.08	6-21-2017	GMC	Added reference to the 112701 Legacy mode.

	FOR INTERNAL DISTRIBUTION ONLY				PAGE DATE	4 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		REV 1.08
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			BY	GMC

2. System Overview

2.1. Scope

The Dual Analog to CAN with Accelerometer is designed to monitor two analog inputs and transmit the information on the CAN bus. It has the ability to allow the user to select how the analog inputs and reference voltages are configured. The user can select each channel to read a 0-5 volt signal, 0-30 volt signal, Battery monitor, 4-20mA signal, Thermistor signal, Temperature signal, and one channel can be set to read a frequency. (Note: Temperature, 0-30, and Battery are only available starting with hardware revision F and software version 3.1) The user can select if the channel reference voltage is enabled or disabled. If the reference is enabled it can be selected to deliver a 5 volt or a 9 volt output. The module also is an accelerometer that can be used as a inclinometer or impact sensor that reads g-forces in 2 axis and transmit the information to the ES-Key network.

2.2. Part numbers

Dual Analog to CAN with Accelerometer Hale – p/n 610-00033

3. Operation

3.1. Module Operation

For detailed operation of each module type (see section 7).

3.2. LED indications

The module uses LEDs to show the device address, power status, and communication status (see section 16).

3.3. Magnetic switches

The module has two magnetic switches (SWITCH 0 and SWITCH 1). The switches are activated by touching a magnet to either side of the module (see section 6.2).

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	5 of 31
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017
	PRODUCT		Dual Analog to CAN with Accelerometer		REV	1.08
					BY	GMC

3.4. Show device address

The device address will be displayed for 5 seconds if the show device address password is entered (see section 6.1). The address is represented by the 4 ADD LED's in a binary number format. NOTE: Address 0 will flash all the LED's

ADD 8	ADD 4	ADD 2	ADD 1	ADDRESS #
FLASH	FLASH	FLASH	FLASH	0
OFF	OFF	OFF	ON	1
OFF	OFF	ON	OFF	2
OFF	OFF	ON	ON	3
OFF	ON	OFF	OFF	4
OFF	ON	OFF	ON	5
OFF	ON	ON	OFF	6
OFF	ON	ON	ON	7
ON	OFF	OFF	OFF	8
ON	OFF	OFF	ON	9
ON	OFF	ON	OFF	10
ON	OFF	ON	ON	11
ON	ON	OFF	OFF	12
ON	ON	OFF	ON	13
ON	ON	ON	OFF	14
ON	ON	ON	ON	15

4. Analog Channel Setup

4.1. Channel Configuration

When used in normal operation the user has the ability to select how the analog input channel and corresponding reference outputs will work. The user has the ability to set the channels for the following operation by entering a password (see section 6.2) or set the channels from a CAN message (see section 7.6).

4.1.1. Analog Input Channel 0

- 0-5 volt input
- 4-20mA input
- Thermistor Input with a top end of 2.80K
- Frequency input (Only 5 volt Peak to Peak signal capable)
- 0-30 volt input (Note: Available on Revision F or greater Hardware starting with software version 3.1.)
- Battery Monitor (Note: Available on Revision F or greater Hardware starting with software version 3.1.)
- Temp Sensor (Note: Available on Revision F or greater Hardware starting with software version 3.1 and used for reading a temp sensor Hale part number 115722.)

4.1.2. Analog Input Channel 1

- 0-5 volt input
- 4-20mA input
- Thermistor Input with a top end of 2.80K
- Frequency input
- 0-30 volt input (Note: Available on Revision F or greater Hardware starting with software version 3.1.)
- Battery Monitor (Note: Available on Revision F or greater Hardware starting with software version 3.1.)
- Temp Sensor (Note: Available on Revision F or greater Hardware starting with software version 3.1 and used for reading a temp sensor Hale part number 115722)

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	6 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

4.1.3. Reference Voltage Channel 0

- Disabled
- Enabled
- 5 volt
- 9 volt

4.1.4. Reference Voltage Channel 1

- Disabled
- Enabled
- 5 volt
- 9 volt

5. Module Configuration

5.1. Module Configuration

The user can select the module operation by entering a password (see section 6.2). The module can be configured for the following operation.

5.1.1. Normal Operation

- Accelerometer functions
 - Inclinometer (2 axis)
 - Impact Sensor (1 axis user selectable)
- 2 user selectable analog inputs
- 1 polarity selectable input
- 1 negative .25amp output

5.1.2. Legacy 113651 Operation

- 2 analog inputs 0-5 volt
- Reference voltage 5 volts

5.1.3. Legacy 113652 Operation

- 2 analog inputs 4-20mA
- Reference voltage 9 volts

5.1.4. Legacy 115819 Operation

- 1 analog input 0-5 volt (used for reading a current sensor Hale part number 115762)
- Reference voltage 9 volts

5.1.5. Legacy 122397 Operation

- 2 analog inputs 0-5 volt (used for reading a temp sensor Hale part number 115722)
- Reference voltage 5 volts

 <p>607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902</p>	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	7 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

5.1.6. Legacy 112701 Operation

- 2 analog inputs 0-30 volt (used for reading battery voltage)

5.1.7. Legacy mixed Operation

- 1 analog inputs 0-5 volt (used for reading a current sensor Hale part number 115762)
- 1 analog inputs 4-20mA
- Reference voltage 9 volt
- Reference voltage 9 volt

6. Passwords

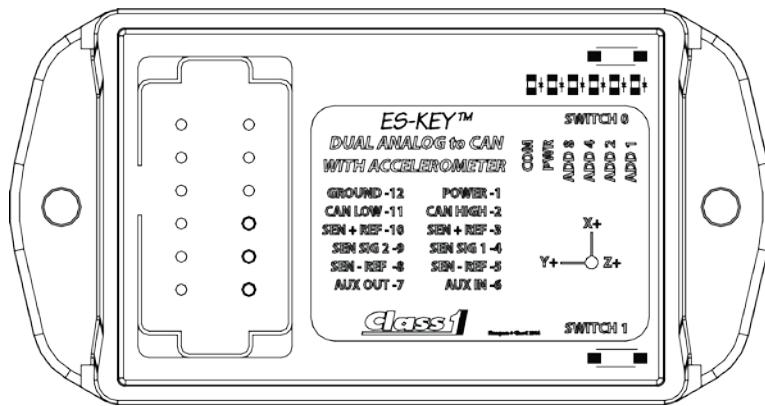
6.1. Password List

1100 0000 (0xC0)	Set module operation to normal
1100 0001 (0xC1)	Set module operation to legacy 113651
1100 0010 (0xC2)	Set module operation to legacy 113652
1100 0011 (0xC3)	Set module operation to legacy 115819
1100 0100 (0xC4)	Set module operation to legacy 122397 (dual channel enable does not apply)
1100 0101 (0xC5)	Set module operation to legacy mixed
1100 0110 (0xC6)	Dual channel enable in legacy mode
1100 0111 (0xC7)	Enable or disable the Accelerometer Impact Feature
1100 1011 (0xCB)	Set module operation to legacy 112701
1000 0001 (0x81)	Calibrate X-axis offset
1000 0010 (0x82)	Calibrate Y-axis offset
1000 0011 (0x83)	Set Input polarity (positive or negative)
1000 0100 (0x84)	Enable-Disable channel 0 reference voltage
1000 0101 (0x85)	Enable-Disable channel 1 reference voltage
1000 0110 (0x86)	Select reference voltage level for channel 0
1000 0111 (0x87)	Select reference voltage level for channel 1
1000 1000 (0x88)	Select Channel 0 analog function
1000 1001 (0x89)	Select Channel 1 analog function
1000 1010 (0x8A)	Zero offset in Legacy O2 mode channel 0
1000 1010 (0x8B)	Zero offset in Legacy O2 mode channel 1
1001 0000 (0x90)	Set The module address.
1001 0001 (0x91)	Show the module address.
1001 0010 (0x92)	Set Accelerometer Axis to read from (X-axis or Y-axis) for impact sensor.
1001 0101 (0x95)	Enter Boot load Mode
1111 0000 (0xF0)	Load Defaults

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	8 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
BY	GMC			DATE	6/21/2017	

6.2. Password Entry

To enter a password, a magnetic switch must activate the two magnetic switches in a specific order. Switch 0 will indicate a 0 from the password list and Switch 1 will indicate a 1 from the password list. When the switch is activated by a magnet, the address LED's will turn on to indicate the switch was activated. Switch 0 will activate ADD 1 and Switch 1 will activate all the ADD LED's. If a password is entered incorrectly or a password is entered that is not in the password list, the ADD LED's will alternate On and OFF to indicate an invalid password was entered.



6.3. Set Module operation to Normal

Enter the password 1100 0000 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.4. Set Module operation to Legacy 113651

Enter the password 1100 0001 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.5. Set Module operation to Legacy 113652

Enter the password 1100 0010 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.6. Set Module operation to Legacy 115819

Enter the password 1100 0011 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.7. Set Module operation to Legacy 122397

Enter the password 1100 0100 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.8. Set Module operation to Legacy 112701

Enter the password 1100 1011 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

 <p>607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902</p>	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	9 of 31
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

6.9. Set Module operation to Legacy Mixed

Enter the password 1100 0101 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved.

6.10. Set Legacy Module operation to use both channels

Enter the password 1100 0110 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: dual channel selection will only work if the module is set to Legacy 113651 or Legacy 113652 mode**)

ADD 8	ADD 4	ADD 2	ADD 1	MODE
OFF	ON	ON	OFF	1-Channel
ON	OFF	OFF	ON	2-Channel

6.11. Enable or Disable the Accelerometer Impact feature

Enter the password 1100 0111 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: will only work if the module is set to Normal mode**)

ADD 8	ADD 4	ADD 2	ADD 1	MODE
OFF	ON	ON	OFF	Disabled
ON	OFF	OFF	ON	Enabled

6.12. Calibrate X-Axis offset

Proper orientation is needed during installation (see section 13.2). Enter the password 1000 0001 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password.

6.13. Calibrate Y-Axis offset

Proper orientation is needed during installation (see section 13.2). Enter the password 1000 0010 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password.

6.14. Zero Channel 0 in Legacy Mode.

Make sure that there is no pressure on the transducer.

Enter the password 1000 1010 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password.

6.15. Zero Channel 1 in Legacy Mode.

Make sure that there is no pressure on the transducer.

Enter the password 1000 0011 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password.

6.16. Input Polarity

Enter the password 1000 0011 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current polarity will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the polarity. Once the desired polarity is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the polarity was saved.

 <p>607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902</p>	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	10 of 31
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017
	PRODUCT	Dual Analog to CAN with Accelerometer		REV	1.08	
				BY	GMC	

ADD 8	ADD 4	ADD 2	ADD 1	Polarity
OFF	ON	ON	OFF	Negative
ON	OFF	OFF	ON	Positive

6.17. Channel 0 Reference Voltage enable

Enter the password 1000 0100 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: will only work if the module is set to normal operation mode**)

ADD 8	ADD 4	ADD 2	ADD 1	Mode
OFF	ON	ON	OFF	Disabled
ON	OFF	OFF	ON	Enabled

6.18. Channel 1 Reference Voltage enable

Enter the password 1000 0101 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: will only work if the module is set to normal operation mode**)

ADD 8	ADD 4	ADD 2	ADD 1	Mode
OFF	ON	ON	OFF	Disabled
ON	OFF	OFF	ON	Enabled

6.19. Channel 0 Reference Voltage setup

Enter the password 1000 0110 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: will only work if the module is set to normal operation mode**)

ADD 8	ADD 4	ADD 2	ADD 1	Mode
OFF	ON	ON	OFF	5 volt
ON	OFF	OFF	ON	9 volt

6.20. Channel 1 Reference Voltage setup

Enter the password 1000 0111 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. (**Note: will only work if the module is set to normal operation mode**)

ADD 8	ADD 4	ADD 2	ADD 1	Mode
OFF	ON	ON	OFF	5 volt
ON	OFF	OFF	ON	9 volt

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	11 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

6.21. Channel 0 Analog Input setup

Enter the password 1000 1000 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. **(Note: will only work if the module is set to normal operation mode)**

ADD 1	0-5 VOLT
ADD 2	4-20mA
ADD 4	Thermistor
ADD 8	Frequency
ADD 1 , ADD 4	0-30 VOLT
ADD 2 , ADD 4	Battery Monitor
ADD 1, ADD 2, ADD 4	Temp Sensor

6.22. Channel 1 Analog Input setup

Enter the password 1000 1001 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password. The current mode will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the mode. Once the desired mode is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. **(Note: will only work if the module is set to normal operation mode)**

ADD 1	0-5 VOLT
ADD 2	4-20mA
ADD 4	Thermistor
ADD 8	Frequency
ADD 1 , ADD 4	0-30 VOLT
ADD 2 , ADD 4	Battery Monitor
ADD 1, ADD 2, ADD 4	Temp Sensor

6.23. Set Address

To enter a device address, first use a magnetic switch and enter the password 1001 0000 (see section 6.2). The current address will be displayed (see section 3.4). Activating Switch 0 will increase the address by 1 every time the switch is activated. Once the desired address is displayed, activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved.

6.24. Set Axis orientation

The Accelerometer is selectable to read in either the X-axis or the Y-axis. Proper orientation is needed during installation (see section 13.2). For the Accelerometer to operate correctly, the orientation for data must be selected by entering the following password 1001 0010 (see section 6.2). The current orientation will be displayed by the 4 ADD LED's (see table). Activating Switch 0 will change the axis. Once the desired axis is selected activating Switch 1 will save the mode and all the ADD led's will flash to indicate the mode was saved. **(Note: will only work if the module is set to normal operation mode)**

ADD 8	ADD 4	ADD 2	ADD 1	AXIS
OFF	ON	ON	OFF	X-AXIS
ON	OFF	OFF	ON	Y-AXIS

6.25. Boot load

The device can have the software upgraded by entering the following password 1001 0101 (see section 6.2). The password must be entered within 30 seconds after the unit is powered up or the boot load password will be disabled.

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	12 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
				BY	GMC	

6.26. Defaults

Enter the password 1111 0000 (see section 6.2). ADD LED's 2 and 4 will flash to acknowledge the password and then all the ADD led's will flash to indicate the mode was saved. When the default password is entered the module will reset to the following operation.

- Normal operation
- Positive input polarity
- Address set to 1
- Analog inputs set to 0-5 volt operation
- Reference voltage output set to 5 volts
- Reference voltage enabled
- X-Axis impact sensor
- default axis offset calibrations.
- Enable the Impact Sensor.

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	13 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

7. Module Operation and Device Network TX RX CAN messages

7.1. Normal Mode

When the module is configured as **Normal Operation** the module operates accordingly

7.1.1. Accelerometer

The module when used as an impact sensor uses ES-Key defined input memory space and is recognized on the ES-Key network as an I/O module device type 4. Every input equals .25g. The user has the ability to disable the Impact sensor (see section 6.10).

The module when used as an inclinometer transmits out the +/- incline data for both x and y axis over the CAN bus. Version 2.9 or Greater sends a dedicated +/- 90 angle (see section 7.7)

7.1.2. Analog Inputs

The module has two analog inputs that transmits a 10 bit raw A2D value over the CAN. Each input can be configured for different analog functionality and each channel has a corresponding voltage reference that can be configured as well (see section 6.16 to 6.21).

7.1.3. Auxiliary Input

The Input is polarity selectable digital input (see section 6.15). The state of the input is transmitted out the CAN bus. When the input is configured as a positive polarity it will activate when the input is greater than 60% of the system voltage. When the input is a negative polarity the input will activate when the input voltage is less than 20% of the system voltage. In version software 2.5 and newer the user can enter a password (see section 6.10) that will disable the Impact Sensor feature of the Accelerometer to allow the aux input to use ES-Key defined input memory space (see section 8).

7.1.4. Auxiliary Output

The Output is a negative output rated for .250 amps. The output is controlled from ES-Key defined output memory space (see section 8).

The ES-Key device ID for the Accelerometer is $4X_h$ (where X is the address value, 0 through E).

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	14 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08

7.2. TX Input status message (ES-Key designation 0x4X to 0x1E)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF_{16}) Proprietary A
PDU Specific:	255 (FF_{16})
Default Priority:	6
Parameter Group Number (PGN):	61184 ($EF00_{16}$)
Source address:	64-78(40 ₁₆ -4E ₁₆)
<i>Byte 0 – Inputs 0 through 7 state</i>	(input 0 is in the LSb position)
<i>Byte 1 – Inputs 8 through 15 state</i>	(input 8 is in the LSb position)
<i>Byte 2 – Inputs 16 through 23 state</i>	(input 16 is in the LSb position)
<i>Byte 3 – Inputs 24 through 31 state</i>	(input 24 is in the LSb position)
<i>Byte 4 – Channel 0 Analog Input States</i>	
<i>Byte 5 – Channel 1 Analog Input States</i>	
<i>Byte 6 – Aux Input Aux Output State</i>	(High Nibble Aux Output--- Low Nibble Aux Input)
<i>Byte 7 – Aux Input Polarity</i>	(0 = Negative 1 = Positive)

Analog Input states

<i>Bit 0</i>	0-5	<i>Bit 4</i>	Reference Enabled
<i>Bit 1</i>	4-20mA	<i>Bit 5</i>	Reference 5 volt
<i>Bit 2</i>	Thermistor	<i>Bit 6</i>	Reference 9 volt
<i>Bit 3</i>	Frequency	<i>Bit 7</i>	Special

If The Special bit is active the low nibble Bit 0 - Bit 3 will show the current profile

<i>Bit 3</i>	<i>Bit 2</i>	<i>Bit 1</i>	<i>Bit 0</i>	Function
0	0	0	1	0-30
0	0	1	0	Battery
0	0	1	1	Temp Sensor
0	1	0	0	Reserved
0	1	0	1	Reserved
0	1	1	0	Reserved
0	1	1	1	Reserved
1	1	1	1	Reserved

7.3. TX Software Angle message (ES-Key designation 0x4X to 0xA1)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF_{16}) Proprietary A
PDU Specific:	255 (FF_{16})
Default Priority:	6
Parameter Group Number (PGN):	61184 ($EF00_{16}$)
Source address:	64-78(40 ₁₆ -4E ₁₆)

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE 15 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	
	PRODUCT	Dual Analog to CAN with Accelerometer			DATE 6/21/2017

Byte 0 – Accelerometer Axis

0 = X-Axis 1 = Y Axis

Byte 1 – Adjusted Angle

Selected Angle (+/- 90) with increased resolution

Byte 2 – Horizontal Angle

Measured X – Axis (+/- 90)

Byte 3 – Vertical Angle

Measured Y – Axis (+/- 90)

Byte 4 – Z – Angle

Measured Z – Axis (+/- 90)

Byte 5 – Software Version

(high nibble = major rev, low nibble = minor rev)

Byte 6 –

Used for Testing

Byte 7 –

Used for Testing

7.4. TX Software version message (ES-Key designation 0x4X to 0xFF)

Message/Frame Format

SAE J1939 CAN 2.0B (PDU1 Format)

Transmission Repetition Rate:

10 per second

Data Length:

8 Bytes

Data Page:

0

PDU Format:

239 (EF₁₆) Proprietary A

PDU Specific:

255 (FF₁₆)

Default Priority:

6

Parameter Group Number (PGN):

61184 (EF00₁₆)

Source address:

64-78(40₁₆-4E₁₆)

Byte 0 – 0x00

Byte 1 – 0xFF

Byte 2 – 0x00

Byte 3 – 0x00

Byte 4 – Module address

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – 0x00

Byte 7 – 0x00

7.5. TX Software Impact Data message (ES-Key designation 0x4X to 0xAA)

Message/Frame Format

SAE J1939 CAN 2.0B (PDU1 Format)

Transmission Repetition Rate:

10 per second

Data Length:

8 Bytes

Data Page:

0

PDU Format:

239 (EF₁₆) Proprietary A

PDU Specific:

170 (AA₁₆)

Default Priority:

6

Parameter Group Number (PGN):

61184 (EF00₁₆)

Source address:

64-78(40₁₆-4E₁₆)

Byte 0 – X-axis data low byte

Battery Voltage Low Byte in Battery Mode

Byte 1 – X-axis data high byte

Battery Voltage High Byte in Battery Mode

Byte 2 – Y-axis data low byte

Battery Voltage Low Byte in Battery Mode

Byte 3 – Y-axis data high byte

Battery Voltage High Byte in Battery Mode

Byte 4 – System Voltage Low byte

Byte 5 – System Voltage High Byte

Byte 6 – 0x00

Byte 7 – 0x00

System voltage example

0x4EA = 1258 = 12.58 volts

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	16 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
				BY	GMC	

7.6. TX Software Analog data message (ES-Key designation 0x9X to 0xFF)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	255 (FF ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	144-158(90 ₁₆ -9E ₁₆)

Byte 0 – Channel 0 A2D Value Low Byte
Byte 1 – Channel 0 A2D Value High Byte
Byte 2 – Channel 1 A2D Value Low Byte
Byte 3 – Channel 1 A2D Value High Byte
Byte 4 – Flow Rate Low Byte (Channel 0)
Byte 5 – Flow Rate High Byte (Channel 0)
Byte 6 – Flow Rate Low Byte (Channel 1)
Byte 7 – Flow Rate High Byte (Channel 1)

Note: Channel 0 is only capable of a 5 volt peak to peak signal

7.7. TX Software Tilt Angle data message (ES-Key designation 0x9X to 0xA1)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	161 (A1 ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	144-158(90 ₁₆ -9E ₁₆)

Byte 0 – Accelerometer Axis *0 = X-Axis 1= Y-Axis*
Byte 1 – Inclinometer Angle *+/- 90 degree*
Byte 2 –
Byte 3 –
Byte 4 –
Byte 5 –
Byte 6 –
Byte 7 –

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	17 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

7.8. RX USM message (ES-Key designation 0x1E to 0x4X)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	as received
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	64-79 (40 ₁₆ -4F ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF0016)
Source address:	30(1E ₁₆)

Byte 0 – Output 0 *(Output 0 is in the LSb position)*

Byte 1 –

Byte 2 –

Byte 3 –

Byte 4 –

Byte 5 – Command Byte

Byte 6 – Validation Byte (Always 0x23)

Byte 7 – Activate Byte

This message is also used to verify that the module is communicating with the ES-Key Universal System Manager (USM) to determine the proper handling of the communication diagnostic LED (see section 16).

Command Byte

- 0x50 Bootload
- 0x51 Channel 0 Analog Input Configuration
- 0x52 Channel 1 Analog Input Configuration
- 0x53 Set Aux Input polarity
- 0x54 Enable or Disable the Accelerometer Impact Sensor Feature

Validation Byte is always 0x23

Activate Byte 0x01 for BootLoad command

If setting analog channels

High nibble

- 0 = Disable Reference Voltage output.
- 1 = Enable Reference Voltage set at 5 volts
- 2 = Enable Reference Voltage set at 9 volts

Low nibble

- 1 = Set Channel to 0-5 volt input
- 2 = Set Channel to 4-20mA input
- 3 = Set Channel to Thermistor input
- 4 = Set Channel to Frequency (only available on Channel 1)
- 5 = Set Channel to 0-30 volt input
- 6 = Set Channel to Battery Monitor
- 7 = Set Channel to Temp Sensor

Example Activate byte 0x22

Channel set to 4-20mA input with a 9 volt reference.

If setting input polarity 0x00 for negative 0x01 for positive.

If setting the impact sensor state 0x00 will disable 0x01 will enable.

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	18 of 31	
	PRODUCT GROUP ES-Key P/N FSG-MNL-00106					DATE 6/21/2017	
	PRODUCT	Dual Analog to CAN with Accelerometer				REV 1.08	
					BY	GMC	

8. ES-Key Network Detail

8.1. Input/output memory space

The Accelerometer when used as an impact sensor uses ES-Key defined input memory space and is recognized on the ES-Key network as an I/O module device type 4. Every input equals .25g. If the Accelerometer Impact feature is disabled in Normal mode the aux input uses Input Memory Space 0 to report its state to the ES-Key network (see section 6.10)

8.1.1. Standard I/O memory space

INPUT MEMORY SPACE		OUTPUT MEMORY SPACE	
INPUT	DESCRIPTION	OUTP UT	LOCATION
0	Input 0 .25g / Aux Input	0	AUX Output
1	Input 1 .50g	1	reserved
2	Input 2 .75g	2	reserved
3	Input 3 1.00g	3	reserved
4	Input 4 1.25g	4	reserved
5	Input 5 1.50g	5	reserved
6	Input 6 1.75g	6	reserved
7	Input 7 2.00g	7	reserved
8	Input 8 2.25g	8	reserved
9	Input 9 2.50g	9	reserved
10	Input 10 2.75g	10	reserved
11	Input 11 3.00g	11	reserved
12	Input 12 3.25g	12	reserved
13	Input 13 3.50g	13	reserved
14	Input 14 3.75g	14	reserved
15	Input 15 4.00g	15	reserved
16	Input 16 4.25g	16	reserved
17	Input 17 4.50g	17	reserved
18	Input 18 4.75g	18	reserved
19	Input 19 5.00g	19	reserved
20	Input 20 5.25g	20	reserved
21	Input 21 5.50g	21	reserved
22	Input 22 5.75g	22	reserved
23	Input 23 6.00g	23	reserved
24	Input 24 6.25g	24	reserved
25	Input 25 6.50g	25	reserved
26	Input 26 6.75g	26	reserved
27	Input 27 7.00g	27	reserved
28	Input 28 7.25g	28	reserved
29	Input 29 7.50g	29	reserved
30	Input 30 7.75g	30	reserved
31	Input 31 8.00g	31	reserved

Table 1. Standard I/O memory space.

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	19 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
				BY	GMC	

9. Legacy 113651 and Legacy 113652 Operation and Device Network TX RX CAN messages

9.1. Auxiliary Input

The Input is a polarity selectable digital input (see section 6.15). The state of the input is transmitted out the CAN bus. When the input is configured as a positive polarity it will activate when the input is greater than 60% of the system voltage. When the input is a negative polarity the input will activate when the input voltage is less than 20% of the system voltage.

9.2. Auxiliary Output

The Output is a negative output rated for .250 amps.

9.3. Legacy 113651

The **Legacy 113651** module is used to read a 0-5 volt pressure transducer for displaying information. The Legacy 113651 profile will replace the current Hale part number 113651. The analog inputs are configured to be 0-5 volt inputs with a reference voltage of 5 volts. If the device is in single channel mode only channel 0 is used. If in dual channel mode both channel 0 and channel 1 are used. In single channel mode the module address can be set from 0 to 14. In dual channel mode the module address can be set from 0 to 13 and the module transmit in pairs. If the module is set for address X in dual mode the channel 0 information will transmit out address X and channel 1 information will transmit on address X + 1

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through E) Single channel mode.

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through D). Dual channel mode

9.4. Legacy 113652

The **Legacy 113652** module is used to read a 4-20mA pressure transducer (3000 PSI) to display O2 levels. The Legacy 113652 profile will replace the current Hale part number 113652. The analog inputs are configured to be 4-20mA inputs with a reference voltage of 9 volts. If the device is in single channel mode only channel 0 is used. If in dual channel mode both channel 0 and channel 1 are used. In single channel mode the module address can be set from 0 to 14. In dual channel mode the module address can be set from 0 to 13 and the module transmit in pairs. If the module is set for address X in dual mode the channel 0 information will transmit out address X and channel 1 information will transmit on address X + 1.

If needed the individual channels have the ability to enter a password to zero the pressure reading with no pressure on the transducer (see section. 6.12 and 6.13).

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through E) Single channel mode.

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through D). Dual channel mode

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	20 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08

9.5. TX message (ES-Key designation 0x9X to 0xFF)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	255 (FF ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	144-158(90 ₁₆ -9E ₁₆)
<i>Byte 0 – A2D Value Low Byte</i>	
<i>Byte 1 – A2D Value High Byte</i>	
<i>Byte 2 – Configuration Byte</i>	
<i>Byte 3 –</i>	
<i>Byte 4 – Module Type</i>	(value of 1 for 0-5V or value of 2 for 4-20mA)
<i>Byte 5 – Software version</i>	(high nibble = major rev, low nibble = minor rev)
<i>Byte 6 – Calculated Low Byte</i>	(a value from 1 to 20)
<i>Byte 7 – Calculated High Byte</i>	

Configuration

1. Bit 0	(Aux Input State 0 = off 1 = on)
2. Bit 1	(Aux Output State 0 = off 1 = on)
3. Bit 2	(Aux Switch Polarity 0 = neg 1 = pos)
4. Bit 3	(Sensor Error High 0 = off 1 = on)
5. Bit 4	(Sensor Error Low 0 = off 1 = on)
6. Bit 5	(bad_cal 0 = off 1 = on)
7. Bit 6	(Calibration OK Low 0 = off 1 = on)
8. Bit 7	(Calibration OK High 0 = off 1 = on)

9.6. RX message (ES-Key designation 0x9F to 0x9X)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	as received
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	144-158 (90 ₁₆ -9E ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	159(9F ₁₆)

Byte 0 – Command

- 0x2F – Calibrate High
- 0x30 – Calibrate Low
- 0x36 – Set Factory Calibration
- 0x75 – Turn Off Aux Output
- 0x76 – Turn On Aux Output
- 0x76 – Set Aux Switch Polarity

For selected channel (address dependent)
 Not in original 113651 or 113652 module
 Not in original 113651 or 113652 module
 Not in original 113651 or 113652 module

Byte 1 – Validation (0x23 = message approved)

Byte 2 – Activation (0x01 = message approved)

(If setting switch polarity 0x00 = NEG 0x01 = POS)

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	21 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

10. Legacy 115819 Device Network TX RX CAN messages

10.1. Legacy 115819

The **Legacy 115819** module is used to read the InPower DCS35-300-2 current sensor (Hale part number 115762) to display charging current. The Legacy 115819 profile will replace the current Hale part number 115819. The channel 0 analog input is configured to be a 0-5 volt input with a reference voltage of 9 volts. Channel 1 is not used in this configuration.

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through E).

10.2. TX message (ES-Key designation 0x9X to 0xFF)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF_{16}) Proprietary A
PDU Specific:	255 (FF_{16})
Default Priority:	6
Parameter Group Number (PGN):	61184 ($EF00_{16}$)
Source address:	144-158(90_{16} - $9E_{16}$)

Byte 0 – A2D Value Low Byte

Byte 1 – A2D Value High Byte

Byte 2 – N/A

Byte 3 – N/A

Byte 4 – N/A

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – N/A

Byte 7 – N/A

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	22 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
				BY	GMC	

11. Legacy 112701 Device Network TX RX CAN messages

11.1. Legacy 112701

The **Legacy 112701** module is used to read a Battery Voltage. The Legacy 112701 profile will replace the current Hale part number 112701. The analog inputs are configured to be 0-30 volt inputs with no reference voltages. If the device is in single channel mode only channel 0 is used. If in dual channel mode both channel 0 and channel 1 are used. In single channel mode the module address can be set from 0 to 14. In dual channel mode the module address can be set from 0 to 13 and the module transmit in pairs. If the module is set for address X in dual mode the channel 0 information will transmit out address X and channel 1 information will transmit on address X + 1

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through E) *Single channel mode*.

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through D). *Dual channel mode*

11.2. TX message (ES-Key designation 0x9X to 0xFF)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF_{16}) Proprietary A
PDU Specific:	255 (FF_{16})
Default Priority:	6
Parameter Group Number (PGN):	61184 ($EF00_{16}$)
Source address:	144-158(90_{16} - $9E_{16}$)

Byte 0 – A2D Battery Voltage Low Byte

Byte 1 – A2D Battery Voltage High Byte

Byte 2 – N/A

Byte 3 – N/A

Byte 4 – N/A

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – N/A

Byte 7 – N/A

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	23 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

12. Legacy 122397 Device Network TX RX CAN messages

12.1. Legacy 122397

The **Legacy 122397** module is used to read two temperature sensor modules Hale part number 115722 to display ambient temperature. The Legacy 122397 profile will replace the current Hale part number 122397. The analog inputs are configured to be 0-5 inputs with a reference voltage of 5 volts.

The ES-Key device ID for the Module is $9X_h$ (where X is the address value, 0 through F).

12.2. TX message (ES-Key designation 0x9X to 0xFF)

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	255 (FF ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	144-159(90 ₁₆ -9F ₁₆)

Byte 0 – Internal Temp in Celsius

Byte 1 – External Temp in Celsius

Byte 2 – Internal A2D Value High Byte

Byte 3 – Internal A2D Value Low Byte

Byte 4 – Sensor Error

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – External A2D Value High Byte

Byte 7 – External A2D Value Low Byte

Sensor Error

1. Bit 0	Internal Voltage Good	0 = off 1 = on
2. Bit 1	External Voltage Good	0 = off 1 = on
3. Bit 2	Internal Voltage Low	0 = off 1 = on
4. Bit 3	External Voltage Low	0 = off 1 = on
5. Bit 4	Internal Voltage High	0 = off 1 = on
6. Bit 5	External Voltage High	0 = off 1 = on

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	24 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
			BY	GMC		

13. Legacy Mixed Device Network TX RX CAN messages

13.1. Legacy Mixed

The **Legacy Mixed** module uses channel 0 to read the InPower DCS35-300-2 current sensor (Hale part number 115762) to display charging current. Channel 1 is used to read a 4-20mA pressure sensor for displaying O2 levels. The Legacy Mixed profile will replace the current Hale part number 115819 and Hale part number 113652 for 1 O2 bottle. The channel 0 analog input is configured to be a 0-5 volt input with a reference voltage of 9 volts. Channel 1 input is configured to be a 4-20mA input with a 9 volt reference. The module transmits two can addresses in pairs so the module address can only be set from 0 to 13. If the module is set for address X channel 0 information will transmit out address X and channel 1 information will transmit on address X + 1.

The ES-Key device ID for the Module is 9X_h (where X is the address value, 0 through D).

13.2. TX message (ES-Key designation 0x9X to 0xFF) for Channel 0

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	255 (FF ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	144-157(90 ₁₆ -9D ₁₆)

Byte 0 – A2D Value Low Byte

Byte 1 – A2D Value High Byte

Byte 2 – N/A

Byte 3 – N/A

Byte 4 – N/A

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – N/A

Byte 7 – N/A

13.3. TX message (ES-Key designation 0x9X to 0xFF) for Channel 1

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	10 per second
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	255 (FF ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	145-158(91 ₁₆ -9E ₁₆)

Byte 0 – A2D Value Low Byte

Byte 1 – A2D Value High Byte

Byte 2 – Configuration Byte

Byte 3 –

Byte 4 – Module Type

(value of 5 for Mixed)

Byte 5 – Software version

(high nibble = major rev, low nibble = minor rev)

Byte 6 – Calculated Low Byte

(a value from 1 to 20)

Byte 7 – Calculated High Byte

 607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	25 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106		DATE
	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08

Configuration

7. Bit 0	(Aux Input State 0 = off 1 = on)
8. Bit 1	(Aux Output State 0 = off 1 = on)
9. Bit 2	(Aux Switch Polarity 0 = neg 1 = pos)
10. Bit 3	(Sensor Error High 0 = off 1 = on)
11. Bit 4	(Sensor Error Low 0 = off 1 = on)
12. Bit 5	(bad_cal 0 = off 1 = on)
13. Bit 6	(Calibration OK Low 0 = off 1 = on)
14. Bit 7	(Calibration OK High 0 = off 1 = on)

13.4. RX message (ES-Key designation 0x9F to 0x9X) for Channel 1

Message/Frame Format	SAE J1939 CAN 2.0B (PDU1 Format)
Transmission Repetition Rate:	as received
Data Length:	8 Bytes
Data Page:	0
PDU Format:	239 (EF ₁₆) Proprietary A
PDU Specific:	144-158 (90 ₁₆ -9E ₁₆)
Default Priority:	6
Parameter Group Number (PGN):	61184 (EF00 ₁₆)
Source address:	159(9F ₁₆)

Byte 0 – Command

0x2F – Calibrate High	For channel 1
0x30 – Calibrate Low	Not in original 113652 module
0x36 – Set Factory Calibration	Not in original 113652 module
0x75 – Turn Off Aux Output	Not in original 113652 module
0x76 – Turn On Aux Output	Not in original 113652 module
0x77 – Set Aux Switch Polarity	

Byte 1 – Validation (0x23 = message approved)

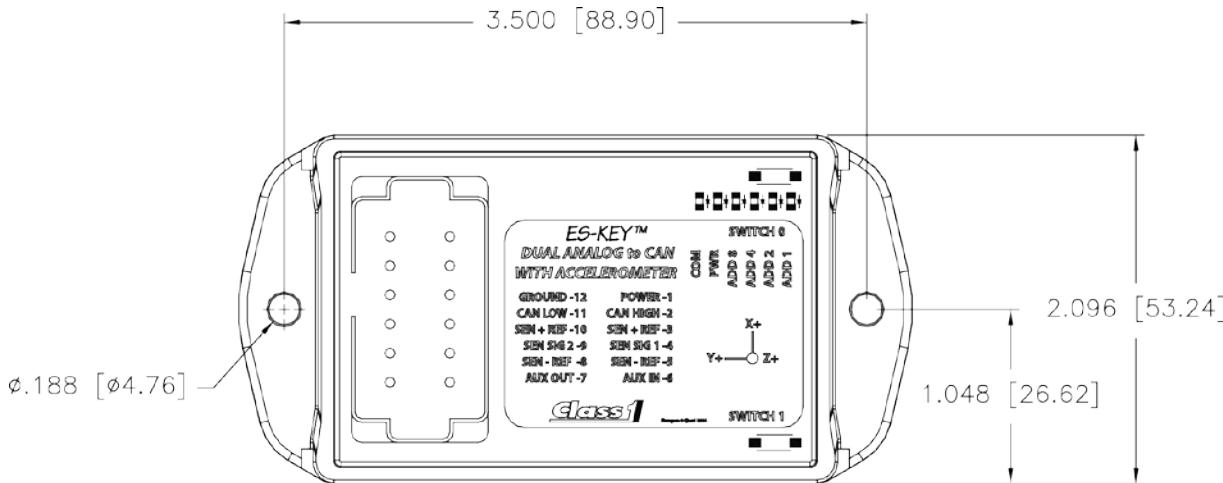
Byte 2 – Activation (0x01 = message approved)

(If setting switch polarity 0x00 = NEG 0x01 = POS)

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	26 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer				REV	1.08
					BY	GMC

14. Installation

14.1. Mounting dimensions

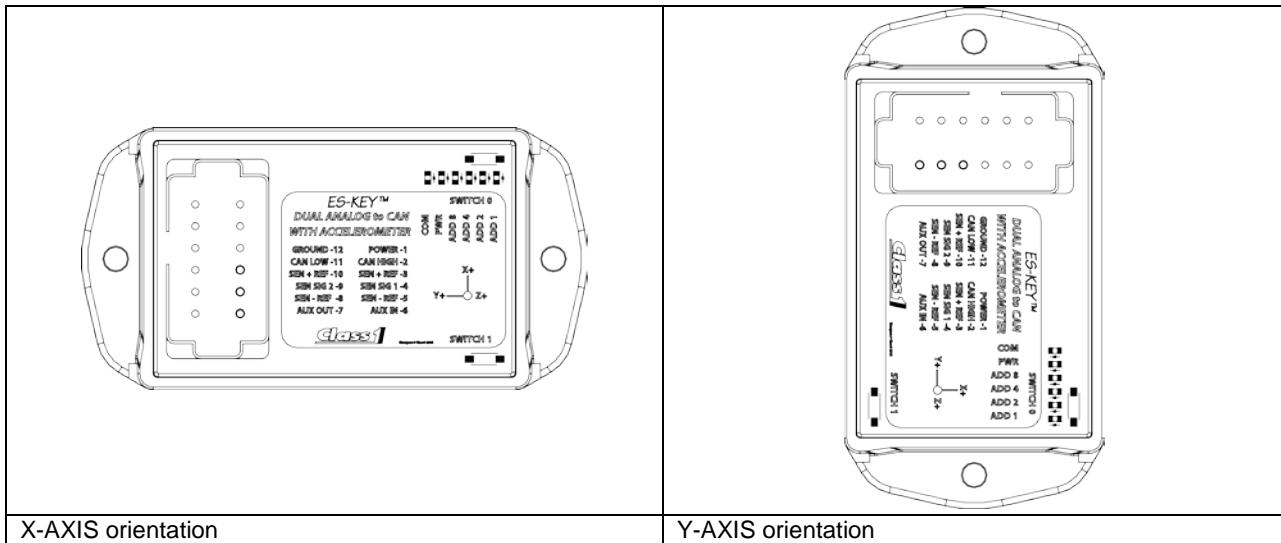


Unit of scale: inches [millimeters]

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	27 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
BY	GMC					

14.2. Mounting orientation

If the unit is to be used as an Accelerometer the unit must be mounted in the desired orientation for either the X-axis or Y-axis operation. Once the desired orientation has been selected the correct password needs to be entered for proper operation (see section 6.2).



	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	28 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
			BY	GMC		

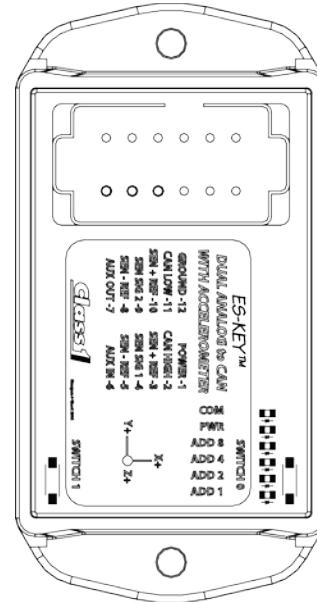
15. Wiring

15.1. Dual Analog to CAN with Accelerometer connector

The Module has one connector and the following definitions apply:

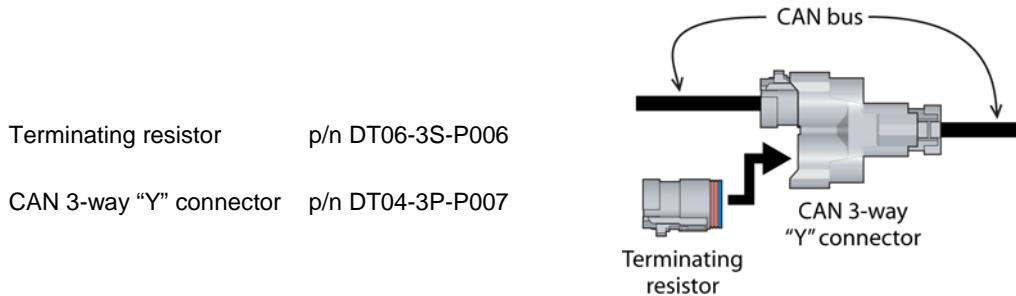
Mating connector: Deutsch DT06-12SA
Mating sockets: Deutsch 0462-201-16141
Wedge lock: Deutsch W12S
Plug Seal: Deutsch 114017
Recommended wire gage: 16-18 AWG

PIN	CIRCUIT	DESCRIPTION
1	SUPPLY (+)	(INPUT) – battery voltage (+9VDC...+32VDC)
2	CAN HIGH	(DATA) – SAE J1939 CAN 2.0B, 250Kbits/s
3	Sensor REF	(OUTPUT) – Selectable +5V or +9V
4	Sensor SIGNAL	(INPUT) – Selectable 0-5V, 4-20mA, Thermistor
5	Sensor GND	(OUTPUT) – Reserved
6	AUX Input	(INPUT) – Selectable Polarity
7	AUX Output	(OUTPUT) – .25A Negative Output
8	Sensor GND	(OUTPUT) – Reserved
9	Sensor SIGNAL	(INPUT) – Selectable 0-5V, 4-20mA, Thermistor, Freq
10	Sensor REF	(OUTPUT) – Selectable +5V or +9V
11	CAN LOW	(DATA) – SAE J1939 CAN 2.0B, 250Kbits /s
12	SUPPLY (-)	(INPUT) – battery ground



15.1.1. Terminating resistor requirement (CAN communication)

Two terminating resistors (120 Ohm) are required on the CAN bus for proper operation (one at each end of the CAN bus). Only two terminating resistors are allowed on a CAN bus.



15.2. System compatibility

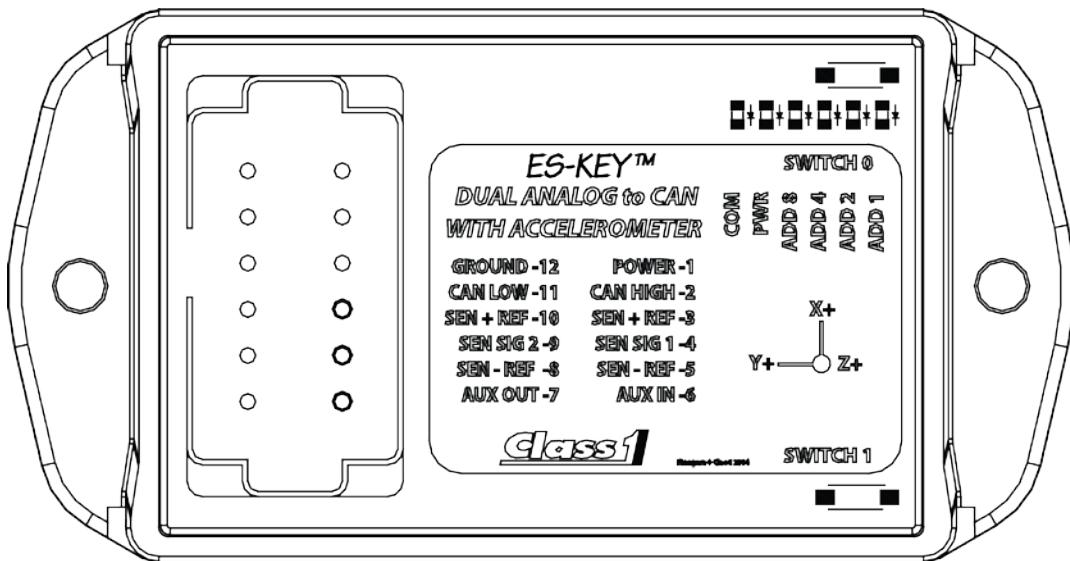
The Dual Analog to CAN with Accelerometer is compatible with other Class 1 CAN devices.

	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	29 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer				REV	1.08
BY	GMC					

16. Upgrade from a 123394 Accelerometer to the new 610-00033 Dual Analog to CAN module with Accelerometer

Upgrade from a 123394 Accelerometer Module to a 610-00033 Dual Analog to CAN Module with Accelerometer:

The new 610-00033 no longer uses pin 10 for the CAN Shield. If a new 610-00033 is being used to replace or upgrade an existing 123394 installation then the wire installed in pin 10 must be removed.



	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	30 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08	
BY	GMC					

17. Diagnostics

The **Accelerometer module** has 2 diagnostic LEDs which are viewable through the potting compound.

PWR - +9...+32VDC Module power
COM - Module status indicator

The COM LED indicates the module's CAN communication status.

On Solid

Module on-line

Flashing slow (2Hz)

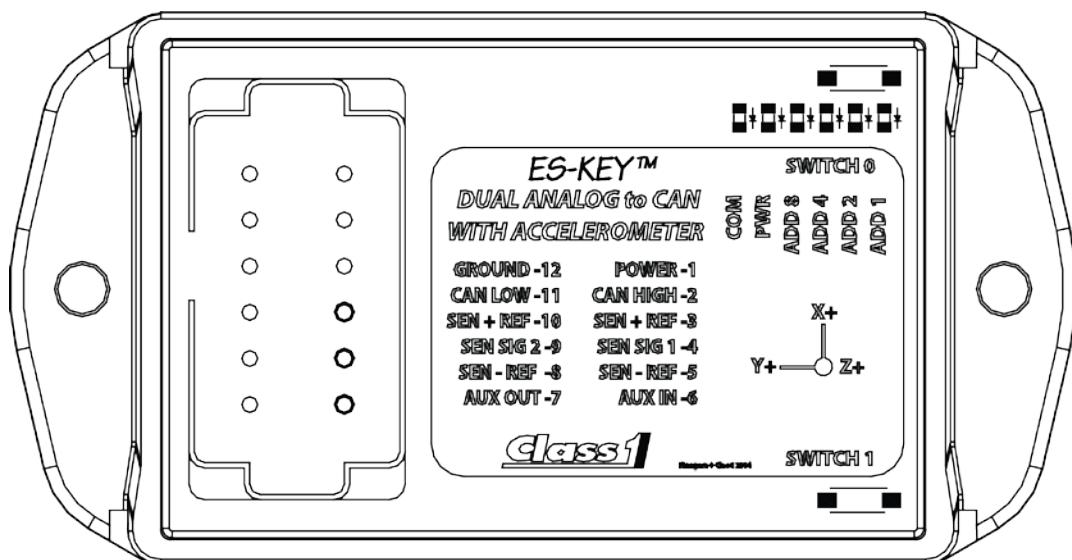
CAN bus okay, but the module is not receiving messages from the Universal System Manager (USM).

Flashing fast (8Hz)

CAN bus error, no communications or not connected.

Double flash

CAN bus has an *ACTIVE* error, no communications.



	FOR INTERNAL DISTRIBUTION ONLY OPERATION MANUAL				PAGE	31 of 31
	PRODUCT GROUP	ES-Key	P/N	FSG-MNL-00106	DATE	6/21/2017
607 NW 27th Ave Ocala, FL 34475 Phone : (352) 629-5020 Fax : (352)-629-2902	PRODUCT	Dual Analog to CAN with Accelerometer			REV	1.08
					BY	GMC

18. Glossary

LED	Light Emitting Diode. The lights on the display used to show tank level and information.
CAN	Controller Area Network. SAE J1939 communication method.
EEPROM	Electrically Erasable Programmable Read-Only Memory. The memory of the tank level display, used to store the display information (tank level points, display type, dim value, etc).
OEM	Original Equipment Manufacturer.
SAE	Society of Automotive Engineers.
ESD	ElectroStatic Discharge.
IP	Ingress Protection (IP 67, etc).
p/n	part number

19. Technical details

19.1. Technical details

Product category	ES-Key
Voltage range	+9VDC...+32VDC
Power consumption	
@ 13.8VDC (25°C)	30 mA
@ 27.6VDC (25°C)	50 mA
Operational temperature range	-40°C...+85°C
Environmental range	IP 67
CAN specification	SAE J1939 proprietary, 250 Kbits/second
	Internal thermal fuse
	Reverse voltage protection (pins 1 and 12 of connector)
Protection	CAN buses protected to 24V
	ESD voltage protected to SAE J1113 specifications
	Transient voltage protected to SAE J1113 specifications
Dimensions (W x H x D) in inches [mm]	3.500 [88.90] x 2.096 [53.24] x .880 [22.35]

19.2. WEEE (Waste of Electrical and Electronic Equipment) directive



This symbol [crossed-out wheeled bin WEEE Annex IV] indicates separate collection of waste electrical and electronic equipment in the European Union countries.
Please do not throw the equipment into the domestic refuse.
Each individual European Union member state has implemented the WEEE regulations into national law in slightly different ways. Please follow your national law when you want to dispose of any electrical or electronic products.

More details can be obtained from your national WEEE recycling agency.